

Listing of Claims

The below listing of claims will replace all prior versions of claims in the application.

1. (Currently Amended) A method for determining a number of a frame in a sequence of two or more frames, the method comprising:

receiving a sequence of at least $M+1$ consecutive OFDM frames, each frame having an index m , having a designated preamble ~~and having wherein the designated preamble has a~~ selected length $N1$ and an associated pseudo-noise signal $PN(t;m)$ ($m = 0, \dots, M; M \geq 1$);

providing an overlap function $OF(m;k)$ of the designated preambles with each of a sequence of selected reference signals, indexed by $k = 1, 2, \dots, K$ where K is a selected integer, and determining a phase $\phi(m)$ corresponding to a location of a maximum amplitude of the overlap functions $OF(m;k)$ for each of the $M+1$ designated preambles of the sequence of at least $M+1$ consecutive OFDM frames;

forming a selected ~~M th-order~~ p th order phase difference of the phases $\phi(m)$; and

comparing the ~~M th-order~~ p th order difference with a selected table of ~~M th-order~~ p th order phase differences to determine a frame number of at least one frame of the $M+1$ consecutive OFDM frames, the frame number uniquely identifying the at least one frame in the $M+1$ consecutive OFDM frames.

2. (Currently Amended) The method of claim 1, further comprising ~~choosing $M=1$~~ choosing $p=1$ and choosing said first-order phase difference to be $\Delta_1(m) = \phi(m+1) - \phi(m)$.

3. (Currently Amended) The method of claim 1, further comprising ~~choosing $M=3$~~ choosing $p=3$ and choosing said ~~first-order~~ third-order phase difference to be $\Delta_3(m) = \phi(m+3) - 3\phi(m+2) + 3\phi(m+1) - \phi(m)$.

4. (Currently Amended) The method of claim 1, further comprising ~~choosing M~~ choosing p to be an odd integer.

5. (Original) The method of claim 1, further comprising forming a linear combination

$$LC(m) = \sum_P c(p) \cdot \Delta_p(m) \quad (P \geq 2),$$

$$p=1$$

where $c(p)$ are selected coefficients, at least one of which is non-zero; and

comparing the linear combination value $LC(m)$ with a selected table of linear combination values to determine a frame number of at least one of the $M+1$ frames.

6. (Original) The method of claim 1, further comprising providing at least two of said pseudo-noise signals, $PN(t;m1)$ and $PN(t;m2)$, as translations of each other through a relation $PN(t;m2) = PN(t + \Delta t(m1,m2);m1)$, where $\Delta t(m1,m2)$ is a selected time difference depending upon at least one of said indices $m1$ and $m2$.

7. (Original) The method of claim 1, further comprising:

computing a first order sum $\sum_1(m) = \phi(m+1) + \phi(m)$ for at least one index number m ;

and

when the sum $\sum_1(m)$ is not equal to at least one of the numbers $+1$ and -1 , adjusting a value of at least said phases $\phi(m)$ and $\phi(m+1)$ so that the sum $\sum_1(m)$ is equal to one of the numbers $+1$ and -1 .

8. (Original) The method of claim 1, further comprising choosing at least one of said selected reference signals to be an m -sequence.

Claims 9-16: (Cancelled).